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THE RESEARCH OF THE OPERATION MODES OF THE DIESEL LOCOMOTIVE CHME3 ON THE IMITATION MODEL

Introduction. Fuel consumption by diesel locomotive during operation depends significantly on many factors, among which the main is the mode of driving a train. **Purpose.** Research on the mathematical model of the modes of driving a train on the site of Kharkiv-Merefa with the purpose of the main oscillograms of the operation of the locomotive on the site. **Methodology.** A mathematical model of the operation of the main units of the locomotive CHME3 in the Matlab environment was developed. The model of the diesel engine is based on the calculated indicator diagram of its operation, which is approximated by a continuous dependence. The control panel operates on a system of conditions, the purpose of which is to maintain the set speed. **Results.** In the course of the simulation, statistical data were obtained on the fuel consumption of the diesel locomotive when it operated on a section with a train of constant mass. Based on the data obtained, a three-dimensional surface is constructed showing the dependence of the fuel consumption on the time of the site's exploration and the maximum speed on the site. **Practical value.** The dependence obtained can be used to optimize the driving behavior of trains along a section. The apparent dependence of fuel consumption on the driver's behavior is the basis for the further development of automatic locomotive speed control systems. References 8, figures 6.

Key words: diesel locomotive, imitation model, diesel engine, traction electric drive, road profile, fuel consumption, train mode.

Разработана имитационная модель тепловоза ЧМЭЗ, которая состоит из дизеля с регулятором числа оборотов коленчатого вала, тягового генератора постоянного тока независимого возбуждения и тягового электрического привода. Проведено тестирование работы имитационной модели на профиле участка пути Харьков - Мерефа, при этом основными ограничениями являются время движения, для данного перегона не должно превышать 45 мин., а также максимальная допустимая скорость, которая для грузовых поездов составляет 80 км/ч. Получена трехмерная поверхность, которая показывает зависимость расхода топлива локомотива от режима ведения поезда машинистом при выполнении одинаковой работы, то есть одинакового времени движения по перегону. Библ. 8, рис. 6. Ключевые слова: тепловоз, имитационная модель, дизель, тяговый электропривод, профиль пути, расход топлива, режим ведения поезда.

Introduction. Efficient use of fuel and energy resources is one of the most important tasks facing the Ukrainian economy. The Law of Ukraine «On Energy Saving» defines the energy efficiency of the economy as one of the main strategic guidelines for long-term state energy policy [1].

Railway transport is one of the largest energy consumers in the country. Energy efficiency in modern conditions is the most important factor in increasing the competitiveness of Ukrainian railways in the domestic and international transport services market. In 2010, the Cabinet of Ministers of Ukraine approved the Transport Strategy of Ukraine for the period up to 2020, aimed, in particular, at optimizing energy consumption in the unconditional performance of cargo transportation services and energy security of the company.

The main share of expenses of fuel and energy resources in the company accounts for traction of trains. Today it is 82 % of the total consumption of electricity and 90 % of diesel fuel [2]. Therefore, emphasis in energy saving is made, first of all, on the main type of activity - the transportation process. In this regard, the issue of energy efficiency is very relevant for the railways and requires further research.

Analysis of literary data and problem definition.

An overview [3] shows that CHME3 locomotives make up 97 % of the entire fleet of shunting locomotives in the Ukrainian railways. In addition to maneuvering at stations, these locomotives are often used for transportation, as well as in the suburban traffic. In the conditions of the introduction of high-speed traffic, the optimization of the modes of data types of trains by

sections is of particular importance. In conditions of increasing the speed of the passage of the site we should not forget about the cost of fuel and energy resources.

As noted in [4], the conditions of the locomotive operation while driving the trains are characterized by a continuous change in traction and speed, and to this also there are sections of the paths with insufficient grip. In this case, the power of the locomotive depends on many circumstances, it varies depending on the speed being implemented, the selected position of the controller of the driver and the degree of weakening of the excitation field. These circumstances allow us to implement very diverse modes of control of traction rolling stock, which often differ from those taken in the traction calculations and specified in the regime cards.

For various modes of operation, the rational driving conditions are essential. It does not allow to recommend one mode of driving a train as optimal for all practically possible traffic conditions in the area, because even on the same site, these conditions often change. In addition, the characteristics of electric machines and specific locomotives, depending on their technical state, may differ in certain respects from the corresponding passport data.

All this creates difficulties in the development and practical use of rational modes of driving trains. However, experience shows that even in the presence of regime maps and the implementation of recommended modes of driving trains, technically justified for some average operating conditions, actual costs of electricity and fuel from different drivers on

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built as a dependence of the change in pressure P in the engine's cylinder on the change in volumes V during the piston's displacement.

For the diesel model, the use of the diagram in the axes P and V is rather uncomfortable, so the diagram is transformed into a diagram in the axes F and S , where F is the force acting on the piston, S is the displacement of the piston. The dependence diagram of the force acting on the piston on the displacement is shown in Fig. 3.

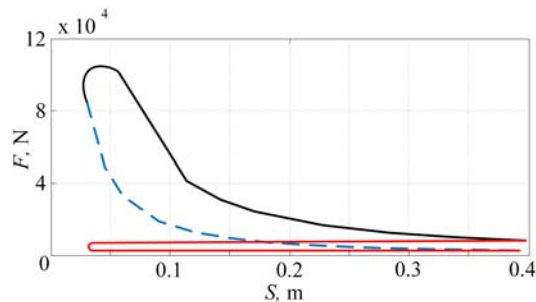


Fig. 3. Operation diagram of the diesel engine K6S310DR

The locomotive has a generator that is a ten-pole DC motor with independent excitation. The power supply of the independent excitation winding of the generator is carried out from the exciter - a machine of direct current connected by a shaft with auxiliary generator.

The block that simulates the traction electric drive includes, in addition to the traction electric motor, blocks that simulate the train's motion in the section and braking of a train.

The model of the resistance blocks of the train's movement is made according to the empirical formulas for the locomotive and cars. The profile of the section Kharkiv-Merefa has been used as a profile of the road. The input parameter for the slope selection block is the path that traveled, which is obtained by integrating the speed of the train.

Input variables for the braking unit operation are the given speed V_s , the current train speed V_t , and the position number of the locomotive driver's controller N_p . To exclude the mode at which braking occurs with operating traction motors, the check of the current position of the handle of the driver's controller is performed. If the position is non-zero, braking does not occur.

The testing of the imitation model was carried out under the parameters given above. Here, the main restrictions were the time of travel, which for the Kharkiv-Merefa section should not exceed 45 minutes, as well as the maximum permissible speed, which for freight trains is 80 km/h. Taking this into account, it is possible to use different intensity of acceleration of the train with the subsequent maintenance of the average speed of the run. Fig. 4 shows two types of train traction tachograms.

In the tachograms shown, t_d is the run-time, which is the same for two tachograms. The change in the intensity of the train's acceleration leads to a change in the maximum speeds that are shown in the diagrams shown as V_{m1} , V_{m2} . In the software package Matlab, using a m-file, a subroutine was written in which the calculation of the intensity of acceleration and train's braking depending on a given maximum speed was performed, subject to the

observance of the driving time of the run. In the study of the operation of the train on the imitation model, tachographs with maximum speeds in the range of 40-80 km/h with step 10 km/h were set. Fig. 5 shows the oscillograms of the shunting diesel locomotive operation with 10 cars, at a maximum speed of 60 km/h.

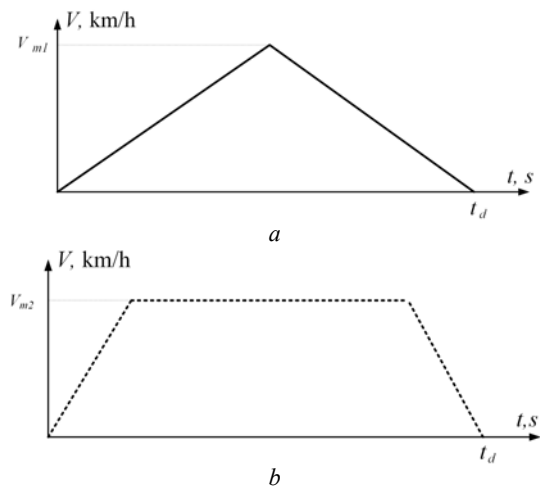


Fig. 4. Types of tachograms of the train acceleration: a - triangular; b - trapezoidal

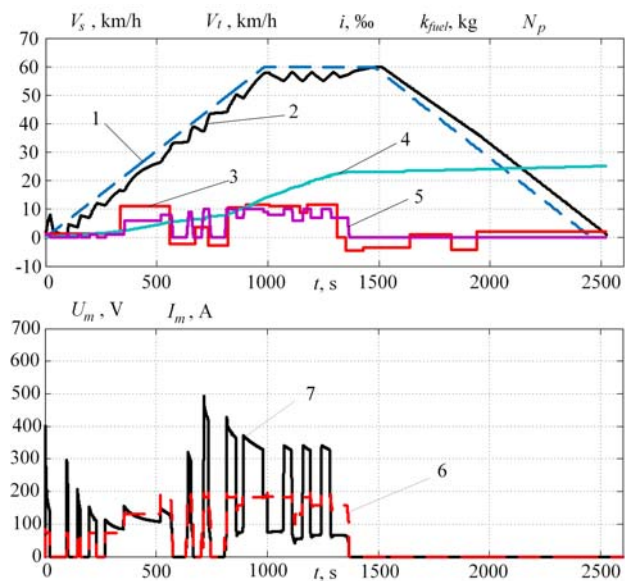


Fig. 5. Oscillograms of the locomotive operation at a maximum speed of 60 km/h: 1 - a tachogram is given; 2 - real speed of the train; 3 - profile of the path; 4 - fuel consumption; 5 - position number of the driver's controller; 6 - voltage on the traction motor; 7 - current of the traction motor

On the obtained oscillograms curve 3 shows the process of set of positions, which varies with different values of maximum speed. Each position corresponds to the change in the voltage on the traction motors (curve 6) and the values of current (curve 7) in them, which was limited to 600 A. The graphs show a tendency to increase fuel consumption with an increase in maximum speed, which requires a more detailed study. Changing the maximum speed of a triangular diagram in the range of 70-95 km/h with step of 5 km/h the results presented in the form of a three-dimensional surface were obtained (Fig. 6).

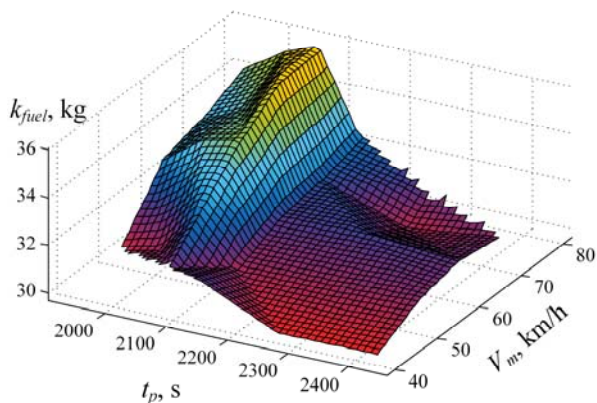


Fig. 6. Changing the fuel consumption depending on the maximum speed of the given diagram

The resulting surface confirms the dependence of the fuel consumption on the locomotive on the train driver's mode of driving (on the time the locomotive operation at a certain position and the intensity of the transition from position to position) when performing the same work, that is, the same time of movement on the run. The smallest fuel consumption, namely 29-31 kg, takes place when the maximum speed is set at 40-50 km/h. Therefore, there is a need to optimize the given train tachogram and develop an automatic control system using a speed regulator that more accurately worked out such a tachogram.

Conclusions. An imitation model of the diesel locomotive CHME3, consisting of a control panel, a diesel engine with a crankshaft speed regulator, an independent excitation DC traction generator and a traction electric drive with sequential excitation DC motors, has been developed. An algorithm is created that simulates the work of the driver, that is, it switches the positions of the controller and controls the brakes. The modeling of the diesel engine is based on the indicator diagram of its operation, which is approximated by continuous dependencies. The obtained imitation model allows obtaining important statistical data for conducting analysis of train driving modes.

A number of operation modes investigations have been carried out when changing the tachogram of speed. Changing the maximum speed of a triangular diagram in the range of 70-95 km/h with step of 5 km/h oscillograms of the locomotive operation with a constant loading on the real section of the road Kharkiv-Merefa are obtained.

From the oscillograms it is seen that the current during motion of the site was lower than the nominal, and in peak modes reached 500 A. Time of passage of the site with a given acceleration rate and speed limit on the level 60 km/h was 2530 s.

The model includes a block that calculates fuel consumption by diesel locomotive. Based on the data obtained from the simulation, a three-dimensional surface is constructed, which reflects the dependence of fuel

consumption on the time of the passage of the site and the maximum speed. It has been established that the smallest fuel consumption, namely 29-31 kg, occurs when the maximum speed is set at 40-50 km/h.

The results obtained during the study show that there is a need to create an automatic control system using a speed controller that more accurately worked out the given tachogram, as well as optimization of train driving modes.

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